CLAIMS

1. A shift control system for controlling gear shifts in a vehicle, comprising:

a transmission;

a controller that detects driving conditions of said vehicle,

that estimates a traction load of said vehicle, that determines a current traction load of said vehicle, and that shifts said transmission based on said current traction load and said estimated traction load if said driving conditions are met.

- The shift control system of claim 1 wherein said shift is a downshift.
- 3. The shift control system of claim 1 wherein said controller determines said current traction load based on a lateral acceleration signal and a longitudinal acceleration signal.
- 4. The shift control system of claim 3 further comprising: a lateral accelerometer that generates said lateral acceleration signal; and
- a longitudinal accelerometer that generates said longitudinal acceleration signal.
 - 5. The shift control system of claim 3 wherein said controller calculates said longitudinal acceleration based on a change in vehicle speed over time.
 - 6. The shift control system of claim 1 wherein said controller estimates said traction load based on a curb weight of said vehicle, a weight transfer gain and an acceleration signal.

- 7. The shift control system of claim 6 further comprising an accelerometer that generates said acceleration signal.
- 8. The shift control system of claim 6 wherein said weight transfer gain represents changes in vehicle weight distribution based on vehicle acceleration.
- 9. A method of controlling automatic transmission shifts in a vehicle, comprising:

detecting driving conditions of said vehicle;
estimating a traction load of said vehicle;
calculating a current traction load of said vehicle; and
commanding a shift based on said current traction load and
said traction load if said driving conditions are met.

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- 10. The method of claim 9 wherein said current traction load is based on a lateral acceleration signal and a longitudinal acceleration signal.
- 11. The method of claim 10 further comprising: generating said lateral acceleration signal with a lateral accelerometer; and

generating said longitudinal acceleration signal with a longitudinal accelerometer.

12. The method of claim 10 wherein said longitudinal acceleration is calculated based on a change in vehicle speed over time.

- 13. The method of claim 9 wherein said theoretical traction load is based on a curb weight of said vehicle, a weight transfer gain and an acceleration signal.
- 14. The method of claim 13 further comprising generating said acceleration signal with an accelerometer.
- 15. The method of claim 13 wherein said weight transfer gain represents changes in vehicle weight distribution based on vehicle acceleration.
- 16. A method of controlling automatic transmission downshift of a vehicle, comprising:

detecting downshift conditions;

estimating a traction load of said vehicle based on a lateral acceleration signal;

estimating a current traction load of said vehicle based on a longitudinal acceleration signal; and

commanding a downshift based on said current traction load and said traction load if said downshift conditions are met.

- 17. The method of claim 16 further comprising:
 generating said lateral acceleration signal with a lateral accelerometer; and
- generating said longitudinal acceleration signal with a longitudinal accelerometer.
 - 18. The method of claim 16 wherein said longitudinal acceleration signal is calculated based on a change in vehicle speed over time.

- 19. The method of claim 16 wherein said traction load is based on a curb weight of said vehicle, a weight transfer gain and an acceleration signal.
- 20. The method of claim 19 further comprising generating said acceleration signal with an accelerometer.
- 21. The method of claim 19 wherein said weight transfer gain indicates changes in vehicle weight distribution based on vehicle acceleration.